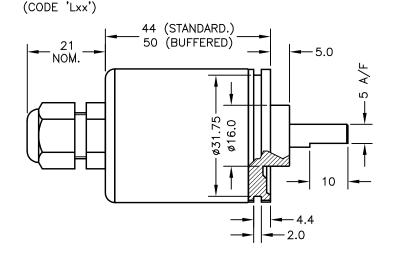
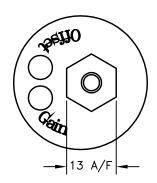


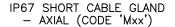
IP67 CABLE GLAND

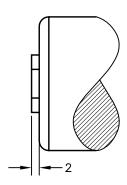




GAIN AND OFFSET ADJUSTMENTS SEALED (CODE 'Y')







N ELEC. OPTIONS AMENDED. PDM O FLANGE TH'KNESS ADDED. PDM P ADDITIONAL DIMS/VIEWS ADDED. PDM Q DISP. 16 TO 160° WAS 20 TO 160° RAN442 PDM R RANGE NOTE AMENDED ~ RAN1200 PDM			
P ADDITIONAL DIMS/VIEWS ADDED. PDM Q DISP. 16 TO 160° WAS 20 TO 160° RAN442 PDM	Ν	ELEC. OPTIONS AMENDED.	PDM
Q DISP. 16 TO 160° WAS 20 TO 160° RAN442 PDM	0	FLANGE TH'KNESS ADDED.	PDM
	Р	ADDITIONAL DIMS/VIEWS ADDED.	PDM
R RANGE NOTE AMENDED ~ RAN1200 PDM	Ø	DISP. 16 TO 160° WAS 20 TO 160° RAN442	PDM
	R	RANGE NOTE AMENDED ~ RAN1200	PDM

DRAWINGS NOT TO BE CHANGED WITHOUT REFERENCE TO THE CHANGE PROCEDURE. CHANGES TO PARTS USED IN INTRINSICALLY SAFE PRODUCT MUST BE APPROVED BY THE AUTHORISED PERSON THIS IS AN UNCONTROLLED PRINT AND WILL NOT BE UPDATED.

ELECTRICAL OPTIONS/ SPECIFICATIONS

SUPPLY CURRENT 12mA TYP. 20mA MAX.

SINK VERSION OUTPUT COMPLIANCE 5-28V SOURCE VERSION DRIVE 3000 MAX TO OV CABLE: 0.2mm², O/A SCREEN, PUR JACKET - SUPPLIED WITH 50cm OR REQUIRED LENGTH IN cm. e.g. 'L50'

4 TO 20mA 3-WIRE SOURCE 24V

CONNECTOR

:1

:3

:4

SPRING RETURN (CODE 'N') AVAILABLE UP TO ±50° CALIBRATED OUTPUT, PHYSICAL STOPS ±55° NOTE STANDARD DEVICE HAS NO STOPS.

0V

*CONNECTORS; MAXIMUM CONDUCTOR CROSS SECTION 0.75mm2

RANGE OF DISPLACEMENT FROM 0-16° TO 0-160° e.g.76°,

OUTPUT

0.5 TO 4.5V RATIOMETRIC

4 TO 20mA 2-WIRE 4 TO 20mA 3-WIRE SINK

CABLE/CONNECTOR* CONNECTIONS;

BODY MATERIAL:— STAINLESS STEEL. FLANGE BASE MATERIAL:— ALUMINIUM. SERVO MOUNT MATERIAL: - ALUMINIUM.

SUPPLY

STANDARD

BUFFERED

57

±15V 24V

±15V

24V

24V

24V

-Ve - OPTIONS: B OR D

BODY - OPTIONS: A, C, E-H

<u>OUTPUT</u>

0.5 TO 9.5V

0.5 TO 4.5V

3-CORE: JACKET Ø4mm 4-CORE: JACKET Ø4.6mm

RED

GREEN

YELLOW

BLUE

3 CORE 4 CORE

SCREEN SCREEN

IN INCREMENTS OF 1°.

FURTHER OPTIONS:

RED

BLACK

WHITE

±5V

±10V

N	18/10/06	4	CHECKED BY		
0	05/01/10	((() (()	RDS	X.X ±0.2 X.XX ±0.1	
Р	06/07/11	7		DIMS mm	
Q	07/11/13	DESCRIPTION			
R	11/09/17	P500 RIPS			
		ROTARY SENSOR			
SCALE 10mm		DRAWING F	2500-11	REV R	
 < > 		SHEET 1 OF 1			

FLANGE BASE SHAFT FLAT ALIGNED WITH REFERENCE MARK IN BASE AT MID TRAVEL ±5°

(CODE 'P')

SERVO MOUNT



P500 ROTARY SENSOR

High-resolution angle feedback for industrial and scientific applications

- Non-contacting inductive technology to eliminate wear
- Angle set to customer's requirement
- Compact, durable and reliable
- High accuracy and stability
- Sealing to IP65/IP67 as required

As a leading designer and manufacturer of linear, rotary, tilt and intrinsically safe position sensors, Positek[®] has the expertise to supply a sensor to suit a wide variety of applications.

Our P500 is an affordable, durable, high-accuracy rotary sensor designed for industrial and scientific feedback applications.

The P500, like all Positek® sensors, is supplied with the output calibrated to the angle required by the customer, between 16 and 160 degrees and with full EMC protection built in. The sensor provides a linear output proportional with input shaft rotation, which has full 360 degree rotational freedom. There is a machined registration mark to identify the calibrated mid point. Overall performance, repeatability and stability are outstanding over a wide temperature range.

It is particularly suitable for OEMs seeking good sensor performance for arduous applications such as industrial machinery where cost is important. The P500 has long service life and environmental resistance with a rugged stainless steel body and shaft, the flange and servo mounts are anodised aluminium. The flange or servo mounting options make the sensor easy to install, it also offers a range of mechanical and electrical options. Environmental sealing is to IP65 or IP67 depending on selected cable or connector options.



SPECIFICATION

Dimensions

Body diameter 35 mm Body Length (to seal face) 44 mm standard, 50 mm buffered

Shaft 15 mm Ø 6 mm

For full mechanical details see drawing P500-11

ndependent Linearity $\leq \pm 0.25\%$ FSO @ 20°C - up to 100° Independent Linearity

 \pm ± 0.25% PSO @ 20°C - up to 100 \pm 0.01%/°C Gain & \pm 0.01%FS/°C Offset > 10 kHz (-3dB) > 300 Hz (-3dB) 2 wire 4 to 20 mA Temperature Coefficients

Frequency response

Infinite Resolution < 0.02% FSO Noise

< 20 mNm Static Torque **Environmental Temperature Limits**

-40°C to +125°C standard -20°C to +85°C buffered -40°C to +125°C Operating

Storage

IP65/IP67 depending on connector / cable option EN 61000-6-2, EN 61000-6-3 Sealing EMC Performance

IEC 68-2-6: 10 g IEC 68-2-29: 40 g 350,000 hrs 40°C Gf Vibration Shock **MTBF Drawing List**

P500-11 Sensor Outline 3D models, step or .igs format, available on request.

Do you need a position sensor made to order to suit a particular installation requirement or specification? We'll be happy to modify any of our designs to suit your needs please contact us with your requirements.



P500 ROTARY SENSOR

High-resolution angle feedback for industrial and scientific applications

How Positek's technology eliminates wear for longer life

Positek's Inductive technology is a major advance in displacement sensor design. Our displacement transducers have the simplicity of a potentiometer with the life of an LVDT/RVDT.

Our technology combines the best in fundamental inductive principles with advanced micro-electronic integrated circuit technology. A Positek sensor, based on simple inductive coils using Positek's ASIC control technology, directly measures absolute position giving a DC analogue output signal. Because there is no contact between moving electrical components, reliability is high and wear is eliminated for an exceptionally long life.

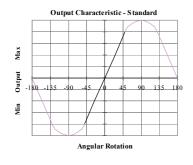
It also overcomes the drawbacks of LVDT technology – bulky coils, poor length-to-stroke ratio and the need for special magnetic materials, no requirement for separate signal conditioning.

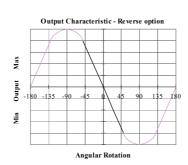
We also offer a range of ATEX-qualified intrinsically-safe sensors.

P500		a	b	С	d	е	f	g
		Displacement	Output	Adjustments	Connections	Option	Option	Z-code

	·	· ·		
a	Displacement		Value	
	tory set to any angle 1 . 0-54°)	from 0-16° (±8°) to 0-160° (±80°)	54	
b	Output			
	Supply V _{dc} (tolerance)	Output	Code	
+5\	V (4.5 - 5.5V)	0.5 - 4.5V (ratiometric with supply)	A	
±1!	5V nom. (±9 - 28V)	±5V	В	
+24	4V nom. (13 - 28V)	0.5 - 9.5V	C	
±1!	5V nom. (±13.5 - 28V)	±10V	D	
+24	4V nom. (18 - 28V)	4 - 20mA 2 wire	E	
+24	4V nom. (13 - 28V)	4 - 20mA 3 wire Sink	F	
+24	4V nom. (9 - 28V)	0.5 - 4.5V	G	
+24	4V nom. (13 - 28V)	4 - 20mA 3 wire Source	Н	
Supp max	oly Current: `A' 10mA nominal . `F' & `H' 32mA nominal, 35m	l, 12mA max. 'B', 'D' & 'G' 12mA nominal, 15mA nA max.	max. `E' 26mA	
С	c Calibration Adjustments Code			
Accessible default			blank	
Sea	Sealed			
d Connections			Code	
Connector IP65 4 pin (3+earth) DIN 43650 'C'			J	
Connector IP65 4 pin (3+earth) DIN 43650 'C' pre-wired			Jxx	
Cable gland IP67 M12, nylon			Lxx	
Cable gland, short [†] IP67, metal			Mxx	
Spec	cify required cable length 'xx' e, 50 cm supplied as standard	in cm. e.g. L2000 specifies axial cable gland wit d. [†] Nb: restricted cable pull strength.	h 20 m of	

e Shaft Option	Code
None default	blank
Sprung to stop up to 100° maximum	N
f Sensor Mounting	Code
Flange default	blank
Servo Mount	P
See drawing P500-11 for details.	
g Z-code (optional)	Code
Connector IP67 M12 IEC 61076-2-101 must have options 'Y' & 'J'	Z600
Connector IP67 M12 IEC 61076-2-101 must have option 'J'	Z601
$\leq \pm~0.1\%$ FSO @20°C Independent Linearity 0 - 16° min. to 0 - 100° max.	Z650





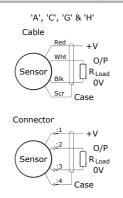
For further information please contact: www.positek.com sales@positek.com

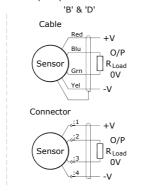


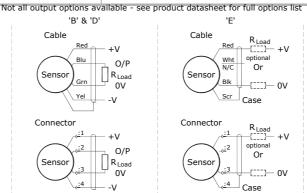
Installation Information P500 ROTARY SENSOR

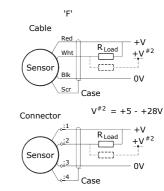
Output Option	Output Description:	Supply Voltage: V _s (tolerance)	Load resistance: (include leads for 4 to 20mA O/Ps)
A	0.5 - 4.5V (ratiometric with supply)	+5V (4.5 - 5.5V)	≥ 5kΩ
В	\pm 5V \pm 15V nom. (\pm 9 - 28V) \geq 5kΩ		≥ 5kΩ
С	0.5 - 9.5V	+24V nom. (13 - 28V)	≥ 5kΩ
D	±10V	±15V nom. (±13.5 - 28V)	≥ 5kΩ
E	4 - 20mA 2 wire Current Loop	+24V nom. (18 - 28V)	≈ 0 - 300Ω max. @24V ~ 1.2 to 6V across 3000 $~\{R_L$ max. = (V_s - 18) / $20^{\text{-3}}\}$
F	4 - 20mA 3 wire Sink	+24V nom. (13 - 28V)	≈ 0 - 950 Ω max. @24V ~ 3.8 to 19V across 950 Ω {RL max. = (Vs - 5) / 20 $^{-3}$ }
G	0.5 - 4.5V	+24V nom. (9 - 28V)	≥ 5kΩ
н	4 - 20mA 3 wire Source	+24V nom. (13 - 28V)	≈ 0 – 300Ω max. ~ 1.2 to 6V across 300Ω









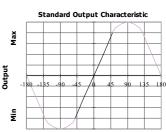


Gain and Offset Adjustment: (Where accessible - Typically \pm 10% Min available) To adjust the gain or offset use a small potentiometer adjuster or screwdriver 2mm across. Do not apply too much force on the potentiometers.

Calibration Adjustments

Mechanical Mounting: Flange mounted or servo mount, with appropriate clips - see drawing P500-11. The sensor should be mounted with minimal axial and radial loading on the shaft for optimum life. It is recommended that the shaft is coupled to the drive using a flexible coupling. Tests indicate that life in excess of 16 million cycles can be achieved with 1kg side and end load. Standard Output Characteristic

Output Characteristic: The sensor has full rotational freedom and two sectors, 180° apart, over which linear response can be achieved. At the mid point of the calibrated range the output signal will be half full scale deflection, and the flat on the shaft is aligned with the registration mark in the base of the sensor. In the calibrated range the output increases as the shaft is rotated in an anti-clockwise direction viewed from the shaft. The calibrated output is factory set to be between 16 and 160°.



Incorrect Connection Protection levels:-

Not protected – the sensor is not protected against either reverse polarity or over-voltage. The risk of Α damage should be minimal where the supply current is limited to less than 50mA.

B&D Supply leads diode protected. Output must not be taken outside \pm 12V. C & G Supply leads diode protected. Output must not be taken outside 0 to 12V.

E, F & H Protected against any misconnection within the rated voltage.